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# **A renormalized perturbation theory for problems with non-trivial boundary conditions or backgrounds in two space–time dimensions**

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**Abstract** We discuss the effects of non-trivial boundary conditions or backgrounds, including non-perturbative ones, on the renormalization program for systems in two dimensions. We present an alternative renormalization procedure in which these non-perturbative conditions can be taken into account in a self-contained and, we believe, self-consistent manner. These conditions have profound effects on the properties of the system, in particular all of its *n*-point functions. To be concrete, we investigate these effects in the  $\lambda \phi^4$  model in two dimensions and show that the mass counterterms turn out to be proportional to the Green's functions which have a non-trivial position dependence in these cases. We then compute the difference between the mass counterterms in the presence and absence of these conditions. We find that in the case of non-trivial boundary conditions this difference is minimum between the boundaries and infinite on them. The minimum approaches zero when the boundaries go to infinity. In the case of non-trivial backgrounds, we consider the kink background and show that the difference is again small and localized around the kink.

#### **1 Introduction**

The procedure of the renormalization with no non-trivial backgrounds or boundary conditions is standard and has been available for over half a century [[1\]](#page-5-0). However, there have been much less investigations done on the renormalization programs for systems which are subject to non-trivial boundary conditions or include non-trivial backgrounds [\[2](#page-5-0)], including non-perturbative ones such as solitary waves or solitons [\[3](#page-5-0)]. It is worth mentioning that for the purposes of

this paper the distinction between the solitary waves and solitons is unimportant and we use them interchangeably. The usual renormalization procedure for systems with such non-perturbative conditions has been either identical to the analogous free cases or has included slight modifications (see for example  $[4-11]$ ). An important example for the case of non-trivial boundary conditions is the calculation of radiative corrections to the Casimir effect. In this case some authors have used free renormalization programs in which the counterterms are directly imported from the free cases or at most supplemented with delta functions on the boundaries [[12\]](#page-5-0). An important example for the case of non-trivial backgrounds is the calculation of quantum corrections to the mass of solitons. In this case the predominant practice has been to use the free renormalization procedure. The main issue that we want to discuss in this paper is that the presence of these non-perturbative conditions has profound effects on all physical properties of the system and the ensuing renormalization procedure. That is, these conditions are an integral part of the overall structure and properties of the theory and obviously cannot be ignored or even taken into account perturbatively. In fact, we believe that the solution to the problem could be self-contained and the renormalization procedure could be done self-consistently considering the nature of the problem.

An additional justification supporting our proposed method is the fact that the presence of these non-perturbative conditions break the translational symmetry of the system. For example, in the presence of a soliton this occurs when we fix the position of the solitons. Obviously the breaking of the translational symmetry has many manifestations. Most importantly, all the *n*-point functions of the theory will have in general a non-trivial position dependence in the coordinate representation. The procedure to deduce the counterterms from the *n*-point functions in a renormalized perturbation theory is standard. This, as we shall show, will lead

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<span id="page-1-0"></span>to uniquely defined position dependent counterterms, which need to be fixed only at one spatial point. Therefore, the radiative corrections to all the input parameters of the theory will be in general position dependent. Therefore, we believe that the information on the non-trivial boundary conditions or position dependent backgrounds is carried by the full set of *n*-point functions, the resulting counterterms, and the renormalized parameters of the theory.

In this paper we set up alternative renormalized perturbation theories for the  $\phi^4$  model in two dimensions for two different cases. First, we consider  $\phi^4$  theory with Dirichlet boundary conditions. One of the most important application of such a theory is the calculation of the radiative corrections of the Casimir effect. Second, we consider  $\phi^4$  theory in the spontaneously broken symmetry phase with the static solitary wave (the kink) as the background. The most common use of this theory is the calculation of the quantum corrections to the mass of the kink. We calculate the mass counterterms in these cases. In both cases we shall inevitably obtain position dependent counterterms. For the first one, our results show that the main difference between the counterterms in the presence and absence of boundary conditions is for positions which are about a Compton wavelength away from the walls, although it has a small value at other places. When the boundaries go to infinity, our counterterm approaches the free one supplemented by delta functions at the boundaries. This is precisely the modified counterterm chosen by [[5–8\]](#page-5-0) for all values of the distance between the plates. In this sense, we believe, the counterterm that the authors of this reference chose is only an approximation to ours. In the second case, we explicitly show that the difference between our mass counterterm in the presence of the kink and the free one is small and is localized around the central position of the kink.

#### **2 The counterterms in the presence of boundary conditions**

In this section we present our alternative approach to the renormalization of a scalar field confined between two points in two space–time dimensions. The Lagrangian density for a real scalar field with  $\phi^4$  self-interaction is

$$
\mathcal{L}(x) = \frac{1}{2} \left[ \partial_{\mu} \varphi(x) \right]^2 - \frac{1}{2} m_0^2 \varphi(x)^2 - \frac{\lambda_0}{4!} \phi(x)^4, \tag{1}
$$

where  $m_0$  and  $\lambda_0$  are the bare mass and bare coupling constant, respectively. The Lagrangian after rescaling the field by  $\phi = Z^{1/2} \phi_r$ , where *Z* is called the field strength renormalization, and invoking the standard procedure for setting up the renormalized perturbation theory, becomes (see for example [\[13](#page-5-0), [14](#page-5-0)])

$$
\mathcal{L}(x) = \frac{1}{2} [\partial_{\mu} \phi_r(x)]^2 - \frac{1}{2} m^2 \phi_r(x)^2 - \frac{\lambda}{4!} \phi_r(x)^4
$$

$$
+\frac{1}{2}\delta Z\big[\partial_\mu\phi_r(x)\big]^2-\frac{1}{2}\delta m^2\phi_r(x)^2-\frac{\delta\lambda}{4!}\phi_r(x)^4,(2)
$$

where  $\delta m^2$ ,  $\delta \lambda$  and  $\delta Z$  are the counterterms, and *m* and  $\lambda$  are the physical mass and physical coupling constant, respectively. We should mention that in these  $1 + 1$  dimensional problems, one usually chooses a minimal renormalization scheme defined at all loops by  $[9-11]$  $[9-11]$  $[9-11]$ 

$$
\delta Z = 0, \qquad \delta \lambda = 0 \quad \text{and} \quad m_0^2 = m^2 - \delta m^2. \tag{3}
$$

The sufficiency of these conditions is supported by the fact that for any theory of a scalar field in two dimensions with non-derivative interactions, all divergences that occur in any order of perturbation theory can be removed by normalordering the Hamiltonian [[15\]](#page-5-0). Complete calculations of all the counterterms in higher dimensions are obviously more complicated and will not be attempted here.

In this problem we are to impose appropriate boundary conditions on the field at the end points. Obviously the presence of non-trivial boundary conditions breaks the translational invariance and hence momenta will no longer be good quantum numbers. Therefore, we find it easier to impose the renormalization conditions in configuration space. For example, the standard expression for the two-point function in the renormalized perturbation theory is

$$
\langle \Omega | T \{ \phi(x_1) \phi(x_2) \} | \Omega \rangle
$$
  
= 
$$
\lim_{T \to \infty} \frac{\langle 0 | \int \mathcal{D} \phi \phi(x_1) \phi(x_2) e^{i \int_{-T}^{T} \mathcal{L}(x) d^4 x} | 0 \rangle}{\langle 0 | \int \mathcal{D} \phi e^{i \int_{-T}^{T} \mathcal{L}(x) d^4 x} | 0 \rangle}.
$$
 (4)

Since the birth of quantum field theory, as far as we know, the assertion has always been that the above expressions can be expanded systematically when the problem is amenable to perturbation theory. For example, in the context of renormalized perturbation theory, as indicated in  $(2)$ , we can symbolically represent the first few terms of the perturbation expansion of (4) by

$$
\sum_{x_1} \bigodot \sum_{x_2} = \sum_{x_1} x_1 + \sum_{x_1} x_2 + \sum_{x_1} x_3 + \sum_{x_1} x_3 + \dots
$$
 (5)

where  $\frac{1}{x_1} \frac{1}{x} \frac{1}{x_2}$  refers to the appropriate counterterm. It is obvious that the above expression represents a systematic perturbation expansion, and most importantly, all of the propagators on the right hand side should be the ones appropriate to the problem under consideration. That is, they should have the same overall functional form as the first term. An integral over space–time is implicitly assumed in the above expression, and the final result is obviously *x*independent. Our first renormalization condition is equivalent to the usual one, which states that the exact propagator should equal the propagator represented by the first term in

[\(5](#page-1-0)) close to its pole. This implies that the second and third diagrams should cancel each other in the lowest order, and this in turn implies the cancellation of the UV divergences to that order. The presence of a space–time integral clouds the central issue at this point. However, considering the higher order diagrams, one can easily conclude that the cancellation of the two aforementioned terms should occur locally. This implies that the counterterms will in general turn out to be position dependent. Therefore, we have

$$
\delta m^2(x) = \frac{-i}{2} \frac{\bigcap}{x} = \frac{-\lambda}{2} G(x, x). \tag{6}
$$

Here  $G(x, x')$  is the propagator of the real scalar field and  $x = (t, z)$ . Obviously the counterterms automatically incorporate the boundary conditions and are position dependent, due to the dependence of the two- and four-point functions on such quantities. An interesting point is that if the propagator for the loop part of  $(5)$  $(5)$  is taken to be the free propagator, i.e. the one with no non-trivial boundary conditions, then the counterterm will turn out to be exactly the free one. However, we have reservations about this procedure. That is, we believe that a self-contained and self-consistent procedure is one in which all of the propagator segments of the above expansion are of the same form, i.e. the one represented by the first diagram. This is strengthened by the symmetry breaking argument presented in the introduction. Consequently the exact functional dependence of  $\delta m^2(x)$  can be completely determined by the theory. That is, the overall structure of the renormalization conditions such as above and the counterterms appearing in them could be determined solely from within the theory, and there is no need, for example, to import them from the free case. The significance of the difference between the counterterms can be illuminated by the following relationship:

$$
m_0^2 = m_{\text{free}}^2 - \delta m_{\text{free}}^2 = m_{\text{bound}}^2 - \delta m_{\text{bound}}^2. \tag{7}
$$

It is extremely important to mention that it is sufficient to fix *m*bound only at one value of *x*.

Now we study very briefly the specific effects of confinement of the system to a finite size by imposing a Dirichlet boundary condition. In order to do this we have to compare the difference between the counterterms of free space and the ones bounded in the interval  $[-\frac{a}{2}, \frac{a}{2}]$ :

$$
\delta m_{\text{bound}}^2(x) - \delta m_{\text{free}}^2 = \frac{-\lambda}{2} \big[ G_{\text{bound}}(x, x) - G_{\text{free}}(x, x) \big]. (8)
$$

For the free space we have  $G_{\text{free}}(x, x') = \int \frac{d^2k}{(2\pi)^2}$  $\frac{e^{-ik(x-x')}}{k^2-m^2+i\epsilon}$ which in Euclidean space leads to

$$
G_{\text{free}}(x,x) = \int \frac{d\omega}{2\pi} \int \frac{dk}{2a} \frac{1}{\omega'^2 + \frac{k^2 \pi^2}{a^2}} = \frac{1}{4\pi} \int \frac{d\omega}{\omega'},\qquad(9)
$$

where  $\omega^2 = \omega^2 + m^2$ . For the bounded problem we have the following expression for the Green's function in the two dimensional Euclidean space:

$$
G_{\text{bound}}(x, x') = \frac{2}{a} \int \frac{d\omega}{2\pi} e^{\omega(t'-t)} \times \sum_{n} \frac{\sin[k_n(z + \frac{a}{2})] \sin[k_n(z' + \frac{a}{2})]}{\omega'^2 + k_n^2}, (10)
$$

where  $k_n = \frac{n\pi}{a}$  is the momentum perpendicular to the plates. Setting  $x' = x$  and using some trigonometric identities, we get

$$
\delta m_{\text{bound}}^2(x) - \delta m_{\text{free}}^2
$$
  
= 
$$
\frac{-\lambda}{8a\pi} \int d\omega \left\{ \frac{a\omega' \coth(a\omega') - 1}{\omega'^2} - 2 \sum_{n=1}^{\infty} \frac{\cos[2k_n(z + \frac{a}{2})]}{\omega'^2 + k_n^2} - \frac{a}{\omega'} \right\}.
$$
 (11)

The summation term in the above equation can be written in terms of hypergeometric functions as follows:

*n*=1

$$
\sum_{n=1}^{\infty} \frac{\cos[2k_n(z+\frac{a}{2})]}{\omega'^2 + k_n^2}
$$
\n
$$
= \frac{iae^{-\frac{2i\pi z}{a}}}{4\omega'(\pi^2 + a^2\omega'^2)}
$$
\n
$$
\times \left\{ (ia\omega' - \pi) \left[ 2F_1 \left( 1, 1 + \frac{ia\omega'}{\pi}, 2 + \frac{ia\omega'}{\pi}, -e^{-\frac{2i\pi z}{a}} \right) \right. \right.
$$
\n
$$
+ e^{\frac{4i\pi z}{a}} {}_2F_1 \left( 1, 1 + \frac{ia\omega'}{\pi}, 2 + \frac{ia\omega'}{\pi}, -e^{\frac{2i\pi z}{a}} \right) \right]
$$
\n
$$
+ (ia\omega' + \pi) \left[ 2F_1 \left( 1, 1 - \frac{ia\omega'}{\pi}, 2 - \frac{ia\omega'}{\pi}, -e^{-\frac{2i\pi z}{a}} \right) \right.
$$
\n
$$
+ e^{\frac{4i\pi z}{a}} {}_2F_1 \left( 1, 1 - \frac{ia\omega'}{\pi}, 2 - \frac{ia\omega'}{\pi}, -e^{\frac{2i\pi z}{a}} \right) \right]. \quad (12)
$$

It is important to note that the counterterm for the bounded case has only a logarithmic ultraviolet divergence, while the free one has an additional infrared divergence in the massless case. The ultraviolet divergences exactly cancel each other for all cases, while the infrared divergence in the massless case remains. The resulting difference between the counterterms,  $(11)$  $(11)$  $(11)$ , is illustrated in Fig. 1 for  $m = 1$ ;  $a = 1$  (m<sup>-1</sup>) and  $\lambda = 0.1$  (m<sup>2</sup>), where 'm' appearing in the parentheses denotes the unit of mass. This figure shows that the difference between the counterterms in the free and bounded cases is minimum in the middle of the plates, and infinite on the plates. It is interesting to note that, for  $m \neq 0$ , as  $a \rightarrow \infty$ , this difference approaches zero for all finite *z*. We can compare our results with  $[5-8]$ , in which the authors

<span id="page-3-0"></span>

**Fig. 1** The difference between the counterterms for the  $\lambda \phi^4$  Dirichlet problem:  $\delta m_{\text{bound}}^2(x) - \delta m_{\text{free}}^2$ , for mass  $m = 1$ ;  $a = 1 \text{ (m}^{-1})$  and  $\lambda = 0.1$  (m<sup>2</sup>). Please, note that this difference is significant only close to the boundaries. At the boundaries this difference diverges logarithmically. When the plate separation goes to infinity this difference approaches zero for all finite *z*

attempt to include finite size effects in their renormalization procedure. The counterterm which they use is just the free counterterm between the plates and delta functions on the plates for all plate separations. This is identical to what we have only in the limit of infinite plate separation. We believe the counterterm that we have obtained within our theory is the one which is appropriate to this problem and their counterterm is only an approximation to ours. We have obtained the first order radiative correction to the Casimir energy using our counterterm [[16,](#page-5-0) [17\]](#page-5-0).

#### **3 The counterterms in the presence of non-trivial backgrounds**

In this section we study the counterterms appropriate for problems with non-trivial backgrounds. One interesting background is the  $\phi^4$  kink. This background has non-trivial boundary values as well as non-trivial spatial variations. We start with the Lagrangian density for a neutral massive scalar field, within  $\phi^4$  theory, appropriate for the spontaneously broken symmetry phase in  $1 + 1$  dimensions:

$$
\mathcal{L} = \frac{1}{2} \left( \frac{\partial \phi}{\partial t} \right)^2 - \frac{1}{2} \left( \frac{\partial \phi}{\partial z} \right)^2 - U \left[ \phi(x) \right],\tag{13}
$$

where  $U[\phi] = \frac{\lambda'_0}{4} (\phi^2 - \frac{\mu_0^2}{\lambda'_0})^2$  and  $\lambda'_0 = \lambda_0/6$ . As is well known [[10\]](#page-5-0), the Euler–Lagrange equation can be easily obtained and is a second order nonlinear PDE with the following solutions: two non-topological static solutions  $\phi_{\text{vac}} =$ :  $v_0 = \pm \mu_0 / \sqrt{\lambda'_0}$ , and two topological static ones  $\phi_{\text{kink}}(z) =$  $\pm \mu_0 / \sqrt{\lambda'_0} \tanh[\mu_0(z - z_0) / \sqrt{2}]$ . These are called kink and antikink solutions, respectively. The presence of an arbitrary

*z*<sup>0</sup> is a manifestation of the translational invariance of the system, and this will lead to a zero mode. However, as mentioned before, fixing *z*<sup>0</sup> will break that symmetry. In order to find the quantum corrections to this mass, we have to make a functional Taylor expansion of the potential about the static solutions, which yields the stability equation,

$$
\left[ -\nabla^2 + \frac{\mathrm{d}^2 U}{\mathrm{d}\phi^2} \bigg|_{\phi_{\text{static}}(z)} \right] \eta(x) = \omega^2 \eta(x),\tag{14}
$$

where we have defined  $\phi = \phi_{static} + \eta$  and  $\omega^2 = k^2 + 2\mu_0^2$ . The results in the trivial sector are the continuum states  $\eta(x) = \exp(i kx)$ . In the kink sector we have the following two localized states and continuum states for the transparent potential in  $(14)$  [[18\]](#page-5-0):

$$
\eta_0(z') = \sqrt{\frac{3m_0}{8}} \frac{1}{\cosh^2 z'},
$$
  
\n
$$
\eta_B(z') = \sqrt{\frac{3m_0}{4}} \frac{\sinh z'}{\cosh^2 z'},
$$
  
\n
$$
\eta_q(z') = \frac{e^{iqz'}}{N_q} [-3 \tanh^2 z' + 1 + q^2 + 3iq \tanh z'],
$$
\n(15)

where  $m_0 = \mu_0 / \sqrt{2}$ ,  $\omega_0^2 = 0$  is for our zero mode,  $\omega_B^2 =$  $\frac{3}{4}m_0^2$  is for our only bound state, and  $\omega_q^2 = m_0^2(\frac{q^2}{4} + 1)$  are for the continuum states. Here  $N_q^2 = 16 \frac{\omega_q^2}{m_0^4} (\omega_q^2 - \omega_B^2)$  and  $z' = m_0 z/2$ .

Now we calculate the mass counterterm in the kink sector by expanding the Lagrangian, which includes the mass counterterm, around the kink background. However, we can set up a more general problem by the following expansion:

$$
\phi(z,t) \to y(z) + \eta(z,t) = \frac{m_0}{\sqrt{2\lambda'_0}} \tanh\left[\frac{m_0}{2}z\right] + \eta(z,t),
$$

where  $y(z)$  can be any of the static solutions, for example the kink solution as indicated above. Then the Lagrangian which includes the mass counterterm becomes

$$
\mathcal{L} = \frac{1}{2} (\partial_{\mu} \phi)^2 + \frac{1}{2} (m^2 - \delta m^2) \phi^2 - \frac{\lambda'}{4} \phi^4 - \frac{(m^2 - \delta m^2)^2}{4\lambda'}
$$
  
\n
$$
= \frac{1}{2} (\partial_{\mu} \eta)^2 + \left(\frac{1}{2} m^2 - \frac{3}{2} \lambda' y^2\right) \eta^2 - \lambda' y \eta^3 - \frac{1}{4} \lambda' \eta^4
$$
  
\n
$$
+ \delta m^2 y \eta - \frac{1}{2} \delta m^2 \eta^2 - \frac{1}{2} (\partial_{\mu} y)^2 + \frac{1}{2} (m^2 - \delta m^2) y^2
$$
  
\n
$$
- \frac{1}{4} \lambda' y^4 - \frac{(m^2 - \delta m^2)^2}{4\lambda'}
$$
  
\n
$$
+ (m^2 y - \lambda' y^3 + \partial_{\mu} y \partial^{\mu}) \eta.
$$
 (16)

<span id="page-4-0"></span>Note that the last term in the above equation, which is proportional to  $\eta$ , vanishes exactly after an integration by parts and using the equation of motion. Therefore, the condition of setting the tadpole equal to zero simply becomes

$$
\bigodot_{\mathbf{x}} = \bigodot_{\mathbf{x}} + \bigotimes_{\mathbf{x}} + \dots = 0. \tag{17}
$$

Accordingly, up to first order in *λ* we obtain

$$
i\delta m^{2}(z,t)y(z) = \frac{1}{2} \left[-i\lambda y(z)\right] G(z,t;z,t),
$$

where  $G(z, t; z', t')$  is the propagator for the particular problem under investigation. We finally obtain the following general result, which is also obtained in the previous section using analogous general arguments but a slightly different method:

$$
\delta m^2(z,t) = -\frac{\lambda}{2} G(z,t;z,t). \tag{18}
$$

Note that the counterterms in general naturally turn out to be position dependent. Since  $G(z, t; z', t')$  is uniquely determined by the nature of the problem, so is  $\delta m^2(z, t)$  via  $(18)$ . We do not expect any time dependence for the counterterms when the system is time translation invariant. The Green's function for this problem in the presence of a kink is

$$
G(z, t; z', t')
$$
  
=  $i \int \frac{d\omega}{2\pi} e^{i\omega(t-t')}$   

$$
\times \left( \sum_{n \neq 0} \frac{\eta_n^*(z)\eta_n(z')}{\omega_n^2 - \omega^2} + \int dk \frac{\eta_k^*(z)\eta_k(z')}{\omega_k^2 - \omega^2} \right),
$$
 (19)

where the sum indicates the contributions of the bound states and the integral the continuum states. Note that the zero mode is neglected since it is only a manifestation of the translational invariance of the system and is to be treated as a collective coordinate [\[10](#page-5-0), [19\]](#page-5-0). The above equation, when the two space–time points are set equal and the  $\omega$  integration is performed, becomes

$$
G(z, t; z, t) = -\frac{\eta_{\rm B}^2(z)}{2\omega_{\rm B}} - \int \frac{dk}{2\pi} \frac{|\eta_k(z)|^2}{2\omega_k}.
$$
 (20)

Calculating this integral is very cumbersome, but we can use an interesting relationship which is the local version of the completeness relation [\[20–22](#page-5-0)]:

$$
\left|\eta_k(z)\right|^2 = 1 - \frac{m}{\omega_k^2 - \omega_B^2} \eta_B^2(z) - \frac{2m}{\omega_k^2} \eta_0^2(z). \tag{21}
$$



**Fig. 2** The difference between the counterterms for the  $\phi^4$  kink problem:  $\delta m_{\text{kink}}^2(z) - \delta m_{\text{free}}^2$ , with mass  $m = 1$  and  $\lambda = 0.1$  (m<sup>2</sup>). Note that this difference is very small and localized at  $z = 0$ , the central position of the kink

Using the above equation, the Green's function is easily computable by performing simple integrals. Putting (21) into  $(20)$  and using  $(18)$ , the mass counterterm in the kink background becomes

$$
\delta m_{\text{kink}}^2(z) = \frac{\lambda}{6\sqrt{3}m} \eta_B^2(z) - \frac{\lambda}{2\pi m} \eta_0^2(z) + \frac{\lambda}{8\pi} \int_{-\infty}^{\infty} dk \frac{1}{\sqrt{k^2 + m^2}},
$$
(22)

which, as expected before, is different from the mass counterterm in the trivial sector, i.e. the last term in  $(23)$ . In fact, it has extra finite *z*-dependent terms due to the presence of the localized states, and obviously this difference tends to zero as  $z \rightarrow \pm \infty$ . An alternative reasoning is that the kink solution also tends to either of the trivial vacuum states as *z* → ±∞. Therefore, the difference between the counterterms becomes

$$
\delta m_{\text{kink}}^2(z) - \delta m_{\text{free}}^2 = \frac{\lambda}{6\sqrt{3}m} \eta_B^2(z) - \frac{\lambda}{2\pi m} \eta_0^2(z). \tag{23}
$$

Note that the zero mode appears in the above expression due to the completeness relationship, (23). However, it does not appear in the Green's function or the field quantization. Figure 2 illustrates this difference for  $m = 1$  and  $λ = 0.1$  (m<sup>2</sup>), where *m* denotes the mass of the scalar particle. We have computed the Casimir energy for this system using this procedure [\[23](#page-5-0)].

#### **4 Conclusions**

In this paper we have studied the effects of non-trivial boundary conditions or backgrounds on the renormalization program for a given system in two dimensions. In

<span id="page-5-0"></span>general these two non-perturbative conditions on the system are non-perturbative effects. In the case of non-trivial backgrounds the effect is certainly non-perturbative when the boundary conditions at the infinities are altered, e.g. in the presence of solitons. We have insisted that the renormalization program could completely take into account the boundary conditions or any possible non-trivial backgrounds which break the translational invariance of the system. We have shown that the problem can be self-contained and the above program is accomplishable. To be more specific, we believe that in principle there is no need to import counterterms from the free theory, or even to supplement them with the ad hoc attachment of extra surface terms, to remedy the divergences inherent in this theory. In general, this breaking of the translational invariance is reflected in the non-trivial position dependence of all the *n*-point functions. As we have shown, this could have profound consequences. For example, in the case of renormalized perturbation theory, the counterterms and hence the radiative corrections to the parameters of the theory, i.e.  $m$  and  $\lambda$ , automatically turn out to be position dependent in our approach. In particular, we have calculated the mass counterterms for both the non-trivial boundary conditions and non-trivial background cases and computed and plotted their differences with the free case in Figs. [1](#page-3-0) and [2.](#page-4-0) We have used this renormalization program to compute the Casimir energies in some cases [16, 17, 23].

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